

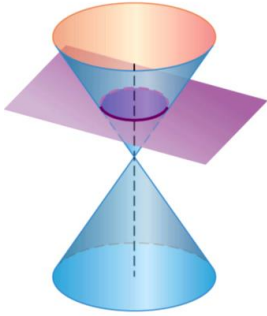
**MA-209**

**Formelhefte**

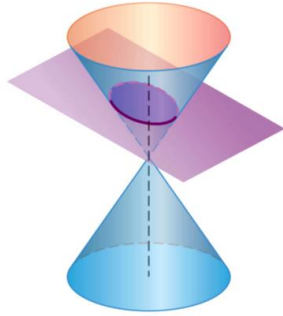
**Per Henrik Hogstad**

**Universitetet i Agder**

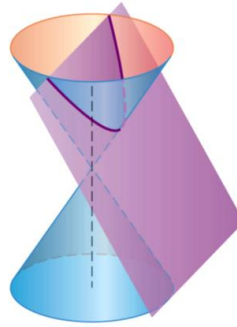
# Kjeglensnitt



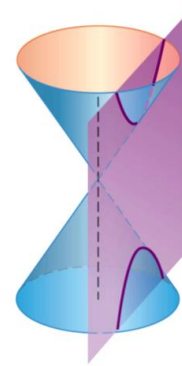
Circle: plane perpendicular to cone axis



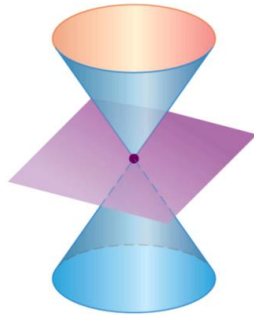
Ellipse: plane oblique to cone axis



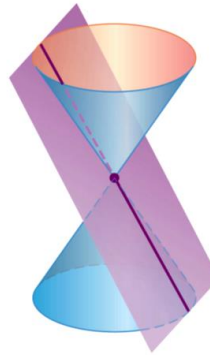
Parabola: plane parallel to side of cone



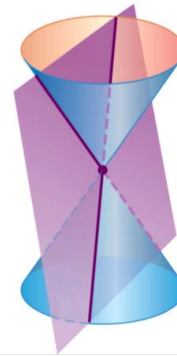
Hyperbola: plane cuts both halves of cone



Point: plane through cone vertex only



Single line: plane tangent to cone



Pair of intersecting lines

**Kvadratisk kurve**

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

$$B^2 - 4AC = 0$$

**Parabel**

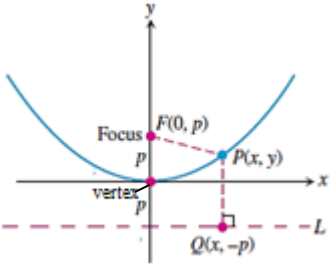
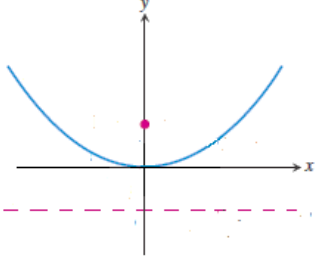
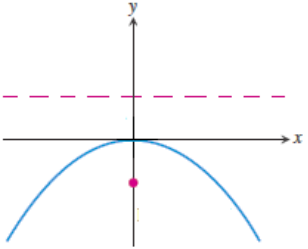
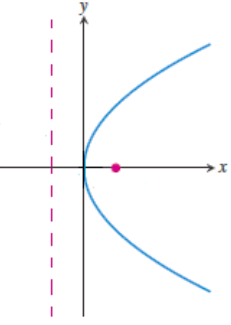
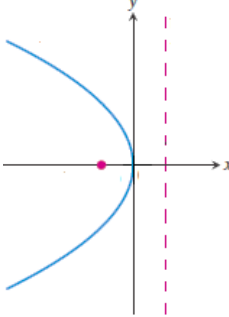
$$B^2 - 4AC < 0$$

**Ellipse**

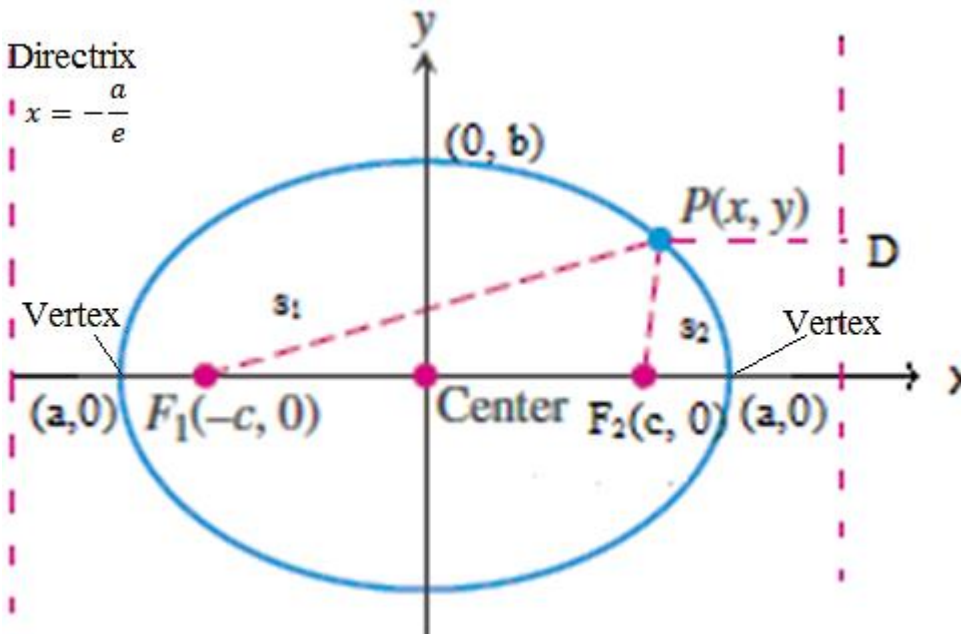
$$B^2 - 4AC > 0$$

**Hyperbel**

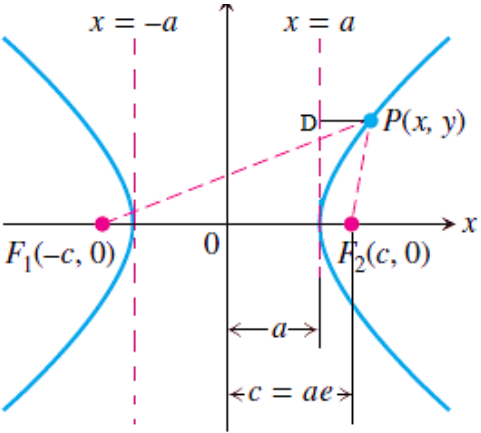
# Kjeglensnitt - Parabel

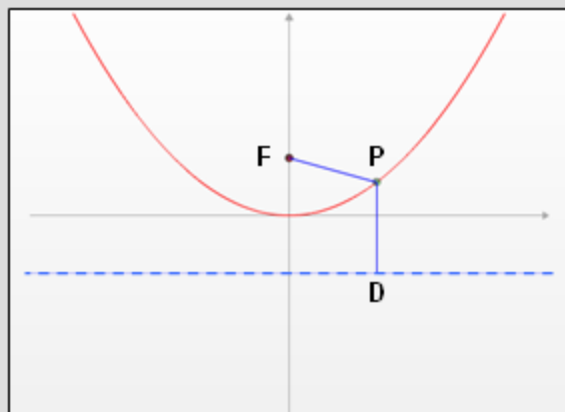
|   |   |   |   |
|---|---|---|---|
| <p><b>Parabel</b></p>   | $y = \frac{1}{4p} x^2$ $PF = PQ$  |    |   |
|  <p style="text-align: center;"><math>x^2 = 4py</math></p> <p>Fokus <math>(0, p)</math></p> <p>Styrelinje <math>y = -p</math></p> |  <p style="text-align: center;"><math>x^2 = -4py</math></p> <p>Fokus <math>(0, -p)</math></p> <p>Styrelinje <math>y = p</math></p> |  <p style="text-align: center;"><math>y^2 = 4px</math></p> <p>Fokus <math>(p, 0)</math></p> <p>Styrelinje <math>x = -p</math></p> |  <p style="text-align: center;"><math>y^2 = -4px</math></p> <p>Fokus <math>(-p, 0)</math></p> <p>Styrelinje <math>x = p</math></p> |
| <p><b>Eksentrisitet</b></p>   | $e = \frac{PF}{PQ} = 1$   |   |   |

Kjeglensnitt - Ellipse

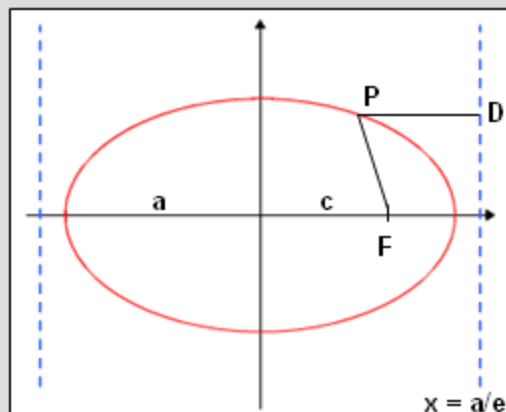
|                             |   |  |
|-----------------------------|---|--|
| <p><b>Ellipse</b></p>       | $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ $s_1 + s_2 = 2a$  |  |
|                             |  <p>Diagram illustrating the geometry of an ellipse centered at the origin of a Cartesian coordinate system. The major axis is along the x-axis, and the minor axis is along the y-axis. The center is labeled "Center". The vertices on the x-axis are labeled "(a,0)" and "(-a,0)". The foci are labeled <math>F_1(-c, 0)</math> and <math>F_2(c, 0)</math>. A point <math>P(x, y)</math> is marked on the ellipse in the first quadrant. Dashed lines represent distances: <math>s_1</math> is the distance from <math>P</math> to <math>F_1</math>, <math>s_2</math> is the distance from <math>P</math> to <math>F_2</math>, and <math>PQ</math> is the perpendicular distance from <math>P</math> to the directrix <math>D</math>. The directrix <math>D</math> is a vertical dashed line on the right. The y-axis is labeled "y" and the x-axis is labeled "X". The top of the ellipse is labeled "(0, b)".</p> |  |
| <p><b>Eksentrisitet</b></p> | $e = \frac{PF}{PQ} = \frac{c}{a} < 1$   |  |

# Kjeglensnitt - Hyperbel

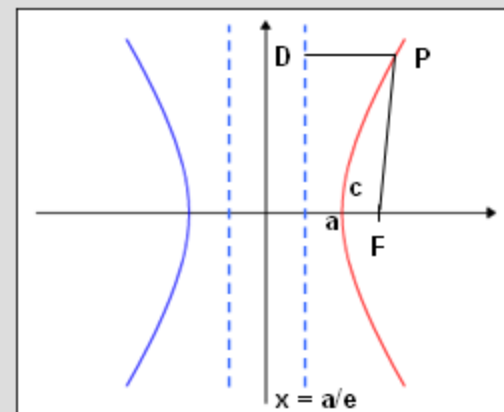
|                             |  |   |
|-----------------------------|--|---|
| <p><b>Hyperbel</b></p>      | $\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ $PF_1 - PF_2 = \pm 2a$ |  <p>The diagram shows a hyperbola opening horizontally on a Cartesian coordinate system. The x-axis is labeled with points <math>F_1(-c, 0)</math> and <math>F_2(c, 0)</math> representing the foci, and the origin <math>0</math>. Vertical dashed lines at <math>x = -a</math> and <math>x = a</math> represent the vertices. A point <math>P(x, y)</math> is marked on the right branch of the hyperbola. A horizontal dashed line segment <math>PD</math> is drawn from <math>P</math> to the x-axis at point <math>D</math>. Red dashed lines connect <math>P</math> to both foci <math>F_1</math> and <math>F_2</math>. Below the x-axis, two horizontal double-headed arrows indicate the distances <math>a</math> (from the origin to the vertex line <math>x = a</math>) and <math>c = ae</math> (from the origin to the focus <math>F_2</math>).</p> |
|                             |  |   |
| <p><b>Eksentrisitet</b></p> | $e = \frac{PF}{PD} = \frac{c}{a} > 1$                          |   |



$$e = \frac{PF}{PD} = 1$$



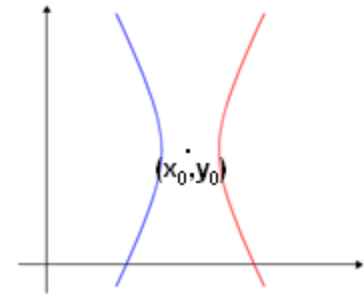
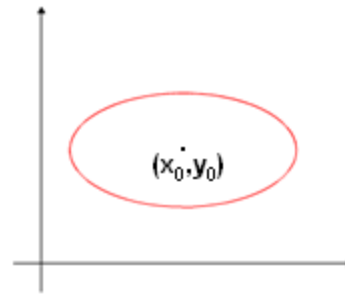
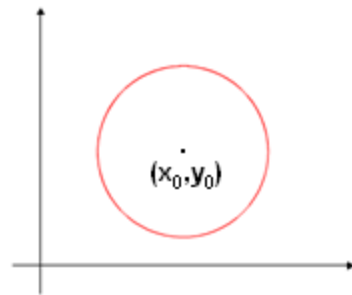
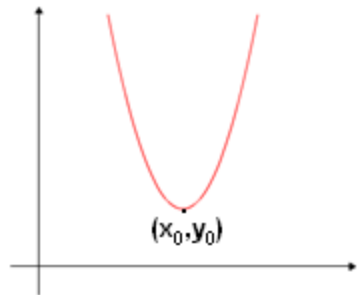
$$e = \frac{PF}{PD} = \frac{c}{a} < 1$$



$$e = \frac{PF}{PD} = \frac{c}{a} > 1$$

$$e = \frac{PF}{PD} = \frac{\text{Avstand fra P til nærmeste fokuspunkt}}{\text{Avstand fra P til nærmeste styrelinje}}$$

Parabel – Sirkel – Ellipse – Hyperbel



**Parabel**

**Sirkel**

**Ellipse**

**Hyperbel**

$$y = y_0 + k(x - x_0)^2$$

$$(x - x_0)^2 + (y - y_0)^2 = R^2$$

$$\left(\frac{x - x_0}{a}\right)^2 + \left(\frac{y - y_0}{b}\right)^2 = 1$$

$$\left(\frac{x - x_0}{a}\right)^2 - \left(\frac{y - y_0}{b}\right)^2 = 1$$

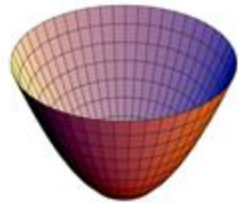
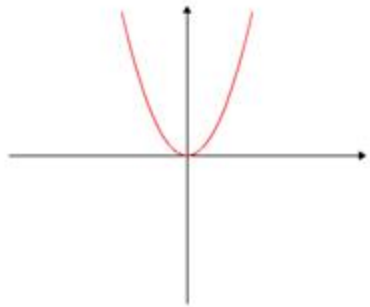
$$B^2 - 4AC = 0$$

$$A = C \quad B = 0$$

$$B^2 - 4AC < 0$$

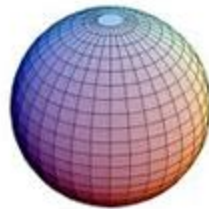
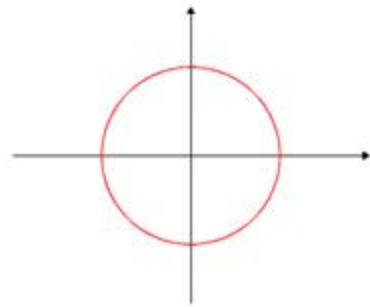
$$B^2 - 4AC > 0$$

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$



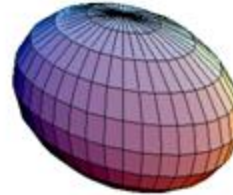
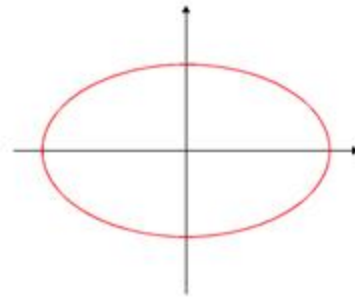
Paraboloide

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - z = 0$$



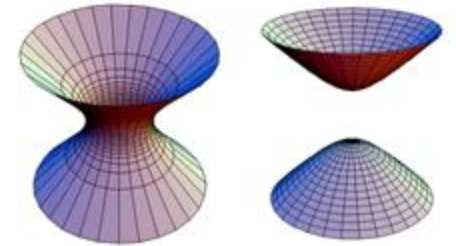
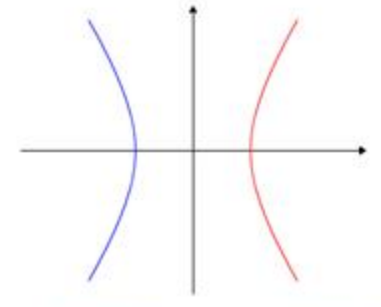
Kule

$$x^2 + y^2 + z^2 = R^2$$



Ellipsoide

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

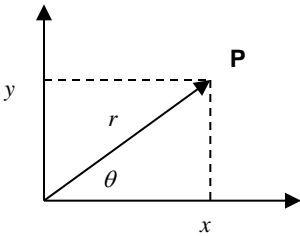
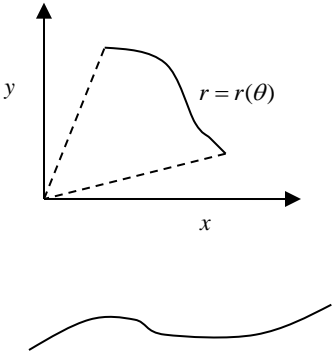
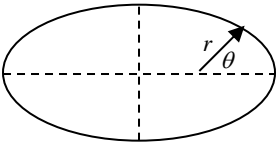


Hyperboloide

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = \pm 1$$



# Polar-koordinater

|  |   |  |
|--|---|--|
| <p><b>Koordinater</b></p>                      | $x = r \cos \theta$ $y = r \sin \theta$ $x^2 + y^2 = r^2$                               |    |
| <p><b>Areal</b></p>                            | $A = \int_{\theta_1}^{\theta_2} \frac{1}{2} r^2 d\theta$                                |    |
| <p><b>Lengden av polar kurve</b></p>           | $L = \int_{\theta_1}^{\theta_2} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$ | <p> <math>e &lt; 1</math>    Ellipse<br/> <math>e = 1</math>    Parabel<br/> <math>e &gt; 1</math>    Hyperbel         </p>  |
| <p><b>Polar ligning for konisk seksjon</b></p> | $r = \frac{ke}{1 + e \cos \theta}$  | <p><b>Ellipse</b></p>  |

Symmetri om x-aksen:

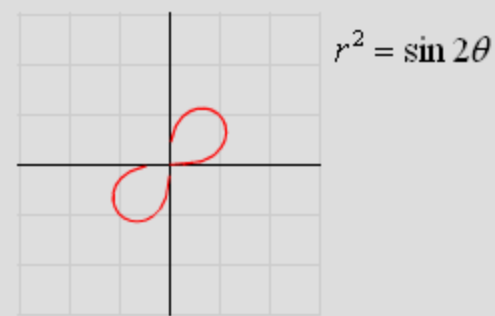
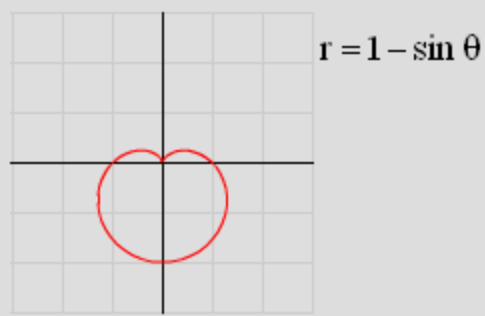
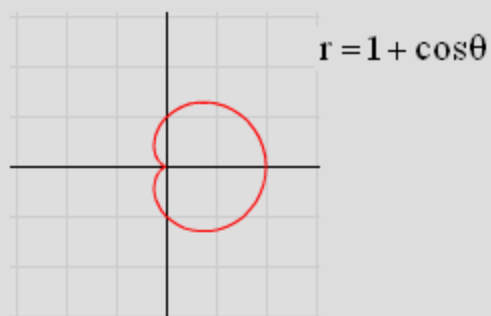
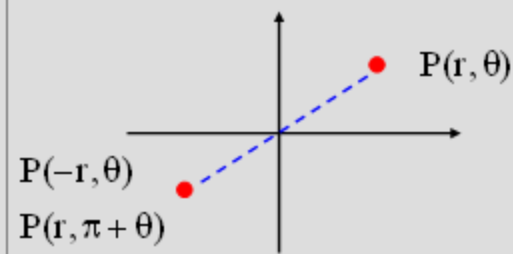
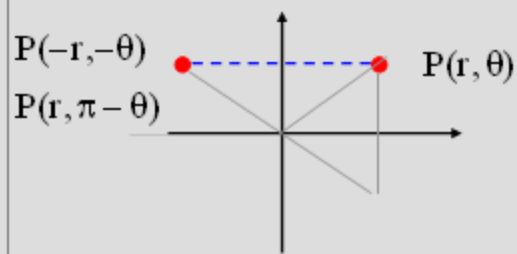
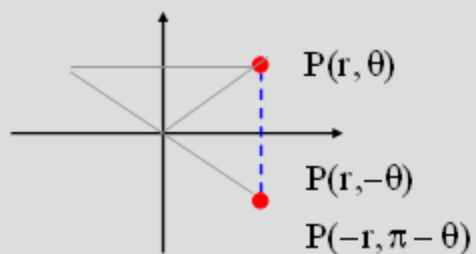
Symmetri om y-aksen:

Symmetri om origo:

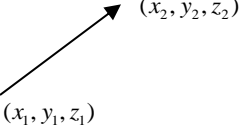
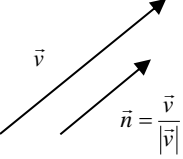
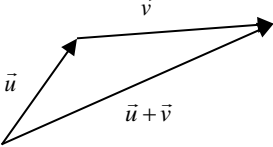
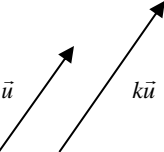
$$r(-\theta) = r(\theta) \quad \vee \quad r(\pi - \theta) = -r(\theta)$$

$$r(-\theta) = -r(\theta) \quad \vee \quad r(\pi - \theta) = r(\theta)$$

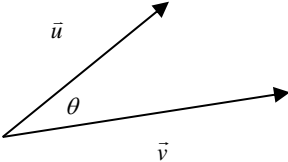
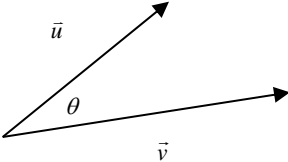
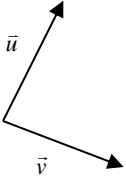
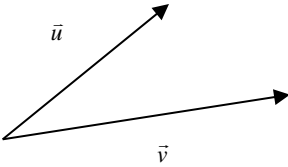
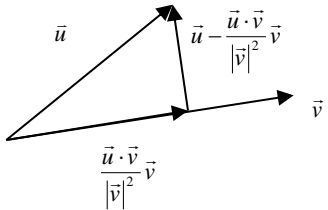
$$r(\theta) = -r(\theta) \quad \vee \quad r(\pi + \theta) = r(\theta)$$



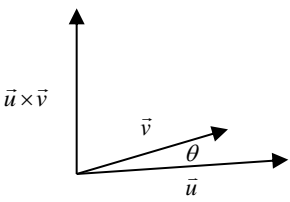
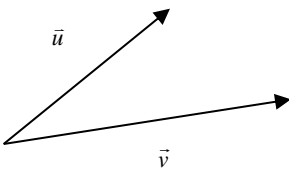
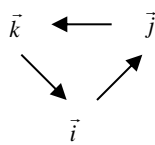

## Vektorer og geometri i rommet - Vektor

|   |  |  |
|---|--|--|
| <p><b>Vektor</b></p>                    | $\vec{v} = (x_2 - x_1)\vec{i} + (y_2 - y_1)\vec{j} + (z_2 - z_1)\vec{k}$ $= [x_2 - x_1, y_2 - y_1, z_2 - z_1]$ $= [v_1, v_2, v_3]$   |  |
| <p><b>Lengden av en vektor</b></p>      | $ \vec{v}  = \sqrt{v_1^2 + v_2^2 + v_3^2}$   |  |
| <p><b>Enhetsvektor</b></p>              | $\vec{n} = \frac{\vec{v}}{ \vec{v} }$  |  |
| <p><b>Addisjon</b></p>                  | $\vec{u} = [u_1, u_2, u_3]$ $\vec{v} = [v_1, v_2, v_3]$ $\vec{u} + \vec{v} = [u_1 + v_1, u_2 + v_2, u_3 + v_3]$  |  |
| <p><b>Multiplikasjon med skalar</b></p> | $\vec{u} = [u_1, u_2, u_3]$ $k\vec{u} = [ku_1, ku_2, ku_3]$  |  |
| <p><b>Regneregler for vektorer</b></p>  | $\vec{u} + \vec{v} = \vec{v} + \vec{u}$ $(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$ $\vec{u} + \vec{0} = \vec{u}$ $\vec{u} + (-\vec{u}) = \vec{0}$ $0\vec{u} = \vec{0}$ $1\vec{u} = \vec{u}$ $a(b\vec{u}) = (ab)\vec{u}$ $a(\vec{u} + \vec{v}) = a\vec{u} + a\vec{v}$ $(a + b)\vec{u} = a\vec{u} + b\vec{u}$ |  |

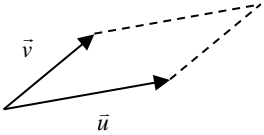
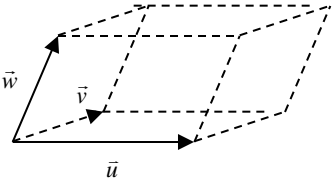
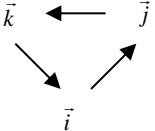
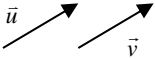
## Vektorer og geometri i rommet - Skalarprodukt

|  |   |  |
|--|---|--|
| <b>Skalarprodukt</b>   | $\vec{u} \cdot \vec{v} =  \vec{u}  \vec{v}  \cos \theta = u_1v_1 + u_2v_2 + u_3v_3$   |    |
| <b>Regler</b>  | $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$ $(c\vec{u}) \cdot \vec{v} = \vec{u} \cdot (c\vec{v})$ $\vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$ $\vec{u} \cdot \vec{u} =  \vec{u} ^2$ $\vec{0} \cdot \vec{u} = 0$ |    |
| <b>Ortogonale vektorer</b>   | $\vec{u} \perp \vec{v} \Leftrightarrow \vec{u} \cdot \vec{v} = 0$   |    |
| <b>Projeksjon av u-vektor på v-vektor</b><br><br><b>Skalarkomponent av u-vektor i retning v-vektor</b> | $proj_{\vec{v}} \vec{u} = \frac{\vec{u} \cdot \vec{v}}{ \vec{v} ^2} \vec{v}$ $ \vec{u}  \cos \theta = \vec{u} \cdot \frac{\vec{v}}{ \vec{v} }$  |    |
| <b>Vektor skrevet som en sum av ortogonale vektorer</b>  | $\vec{u} = \underbrace{\frac{\vec{u} \cdot \vec{v}}{ \vec{v} ^2} \vec{v}}_{\text{Parallell med } \vec{v}} + \underbrace{\left( \vec{u} - \frac{\vec{u} \cdot \vec{v}}{ \vec{v} ^2} \vec{v} \right)}_{\text{Normal på } \vec{v}}$                            |  |

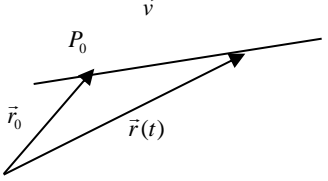
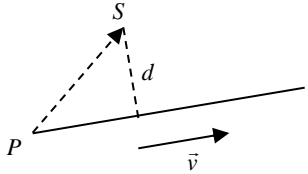
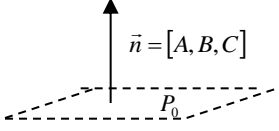
# Vektorer og geometri i rommet - Vektorprodukt

|                                  |   |  |
|----------------------------------|---|--|
| <p><b>Vektorprodukt</b></p>      | $\vec{u} \times \vec{v} =  \vec{u}   \vec{v}  \sin \theta \vec{n}$ $= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$ $= [u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1]$  |    |
| <p><b>Regler</b></p>             | $(r\vec{u}) \times (s\vec{v}) = (rs)\vec{u} \times \vec{v}$ $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$ $(\vec{v} + \vec{w}) \times \vec{u} = \vec{v} \times \vec{u} + \vec{w} \times \vec{u}$ $\vec{v} \times \vec{u} = -(\vec{u} \times \vec{v})$ $\vec{0} \times \vec{u} = \vec{0}$ |    |
|                                  | $\vec{i} \times \vec{j} = \vec{k}$ $\vec{j} \times \vec{k} = \vec{i}$ $\vec{k} \times \vec{i} = \vec{j}$  |    |
| <p><b>Parallele vektorer</b></p> | $\vec{u} \parallel \vec{v} \Leftrightarrow \vec{u} \times \vec{v} = \vec{0}$  |  |

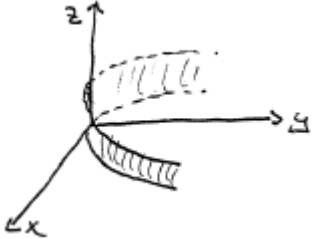
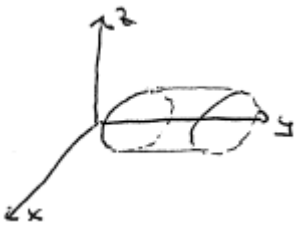
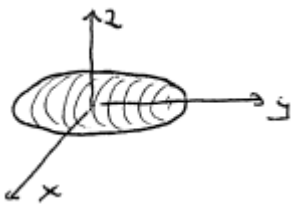

Vektorer og geometri i rommet - Areal - Volum

|                                  |  |  |
|----------------------------------|--|--|
| <p><b>Areal</b></p>              | $A =  \vec{u} \times \vec{v} $   |    |
| <p><b>Volum</b></p>              | $V =  (\vec{u} \times \vec{v}) \cdot \vec{w} $ $= \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$ |    |
|                                  | $\vec{i} \times \vec{j} = \vec{k}$ $\vec{j} \times \vec{k} = \vec{i}$ $\vec{k} \times \vec{i} = \vec{j}$                               |    |
| <p><b>Parallele vektorer</b></p> | $\vec{u} \parallel \vec{v} \Leftrightarrow \vec{u} \times \vec{v} = \vec{0}$   |  |

Vektorer og geometri i rommet - Linjer - Plan

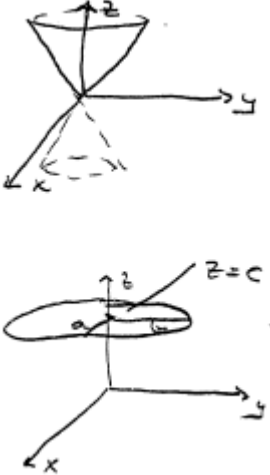
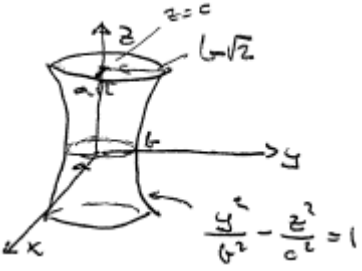
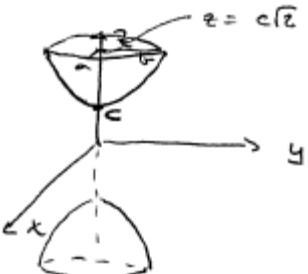
|  |   |  |
|--|---|--|
| <p><b>Linje gjennom <math>P_0</math> parallell med v-vektor</b></p>  | $\vec{r}(t) = \vec{r}_0 + t\vec{v}$ $[x, y, z] = [x_0, y_0, z_0] + t[v_1, v_2, v_3]$ $x = x_0 + tv_1$ $y = y_0 + tv_2$ $z = z_0 + tv_3$ |  |
| <p><b>Avstand fra et punkt S til en linje gjennom P parallell med v-vektor</b></p>                           | $d = \frac{ \vec{PS} \times \vec{v} }{ \vec{v} }$   |  |
| <p><b>Plan gjennom <math>P_0(x_0, y_0, z_0)</math> med normalvektor <math>\vec{n} = [A, B, C]</math></b></p> | $A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$ $Ax + By + Cz = D \quad D = Ax_0 + By_0 + Cz_0$  |  |

Vektorer og geometri i rommet - Kvadratiske flater

|                                    |   |  |
|------------------------------------|---|--|
| <p><b>Kvadratiske flater</b></p>   | $Ax^2 + By^2 + Cz^2 + Dxy + Eyz + Fxz + Gx + Hy + Jz + K = 0$ |  |
| <p><b>Parabolisk sylinder</b></p>  | $y = x^2$   |    |
| <p><b>Elliptisk sylinder</b></p>   | $\frac{x^2}{a^2} + \frac{z^2}{b^2} = 1$                       |    |
| <p><b>Ellipsoide</b></p>           | $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$     |   |
| <p><b>Elliptisk paraboloid</b></p> | $\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z}{c}$             |  |



Vektorer og geometri i rommet - Kvadratiske flater

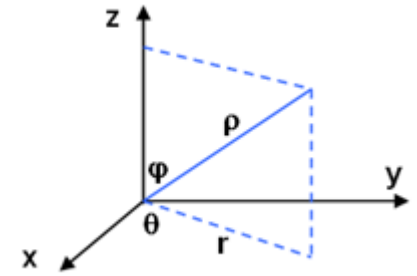
|                         |  |   |
|-------------------------|--|---|
| <p>Elliptisk kjegle</p> | $\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z^2}{c^2}$                      |   |
| <p>Hyperboloide</p>     | <p>En flate</p> $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$  |   |
| <p>Hyperboloide</p>     | <p>To flater</p> $\frac{z^2}{c^2} - \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ |  |

## Vektor-funksjoner

|                                 |  |   |
|---------------------------------|--|---|
| <b>Posisjon</b>                 | $\vec{r}(t)$   |   |
| <b>Hastighet</b>                | $\vec{v}(t) = \vec{r}'(t) = \frac{d\vec{r}(t)}{dt}$  | <b>Fart</b> $\frac{ds}{dt} = v(t) =  \vec{v}(t) $   |
| <b>Akselerasjon</b>             | $\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t) = \frac{d^2\vec{r}(t)}{dt^2}$   |   |
| <b>Enhets tangent vektor</b>    | $\vec{T} = \frac{d\vec{r}}{ds} = \frac{\vec{v}}{ \vec{v} }$  |   |
| <b>Krumning</b>                 | $\kappa = \left  \frac{d\vec{T}}{ds} \right  = \frac{1}{ \vec{v} } \left  \frac{d\vec{T}}{dt} \right  = \frac{ \vec{v} \times \vec{a} }{ \vec{v} ^3}$                        |   |
| <b>Hoved enhets normal</b>      | $\vec{N} = \frac{1}{\kappa} \frac{d\vec{T}}{ds} = \frac{\frac{d\vec{T}}{dt}}{\left  \frac{d\vec{T}}{dt} \right }$  |   |
| <b>Binormal</b>                 | $\vec{B} = \vec{T} \times \vec{N}$   |   |
| <b>Torsjon</b>                  | $\tau = -\frac{d\vec{B}}{ds} \cdot \vec{N} = \frac{\begin{vmatrix} \dot{x} & \dot{y} & \dot{z} \\ \ddot{x} & \ddot{y} & \ddot{z} \end{vmatrix}}{ \vec{v} \times \vec{a} ^2}$ |   |
| <b>Akselerasjonskomponenter</b> | $\vec{a} = a_T \vec{T} + a_N \vec{N}$  | $a_T = \frac{d}{dt}  \vec{v} $<br>$a_N = \kappa  \vec{v} ^2 = \sqrt{ \vec{a} ^2 - a_T^2}$ |

## Koordinatsystemer

|  |   |
|--|---|
| <p><b>Sylindrisk →<br/>Rektangulær</b></p>                               | $x = r \cos \theta$ $y = r \sin \theta$ $z = z$   |
| <p><b>Sfærisk →<br/>Rektangulær</b></p>                                  | $x = \rho \sin \varphi \cos \theta$ $y = \rho \sin \varphi \sin \theta$ $z = \rho \cos \varphi$ |
| <p><b>Sfærisk →<br/>Sylindrisk</b></p>                                   | $r = \rho \sin \varphi$ $\theta = \theta$ $z = \rho \cos \varphi$                               |
| <p><b>Rektangulær</b></p> <p><b>Sylindrisk</b></p> <p><b>Sfærisk</b></p> | $dV = dx dy dz$<br>$dV = dz r dr d\theta$<br>$dV = \rho^2 \sin \varphi d\rho d\varphi d\theta$  |



## Vektor-felt - Del-operator

|                             |  |
|-----------------------------|--|
| <b>Funksjon</b>             | $f = f(x, y, z)$   |
| <b>Vektor-felt</b>          | $\vec{F} = [F_1, F_2, F_3]$  |
| <b>Potensial-funksjon f</b> | $\vec{F} = \nabla f$   |
| <b>Del-operator</b>         | $\nabla = \left[ \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right]$  |
| <b>Gradient</b>             | $\nabla f = \left[ \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right]$  |
| <b>Divergens</b>            | $\text{div} \vec{F} = \nabla \cdot \vec{F} = \left[ \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right] \cdot [F_1, F_2, F_3] = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$   |
| <b>Curl</b>                 | $\text{curl} \vec{F} = \nabla \times \vec{F} = \left[ \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right] \times [M, N, P] = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left[ \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right]$ |

# Kurve-integral

|   |   |   |   |   |   |           |             |   |   |   |                            |        |
|---|---|---|---|---|---|-----------|-------------|---|---|---|----------------------------|--------|
| <b>Kurve-integral</b>   | $\int_C f(x, y, z) ds = \int_a^b f(g(t), h(t), k(t))  \vec{r}'(t)  dt$  | <b>Kurve-lengde</b> $\int_C ds = \int_a^b  \vec{r}'(t)  dt$         |   |   |   |           |             |   |   |   |                            |        |
| <b>Arbeid</b>   | $W = \int_C \vec{F} \cdot \vec{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy + F_3 dz$   |   |   |   |   |           |             |   |   |   |                            |        |
| <b>Strømning</b>  | $\int_C \vec{F} \cdot \vec{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy$  | <b>I planet</b>   |   |   |   |           |             |   |   |   |                            |        |
| <b>Sirkulasjon</b>  | $\oint_C \vec{F} \cdot \vec{T} ds = \oint_C \vec{F} \cdot d\vec{r} = \oint_C F_1 dx + F_2 dy$   |   |   |   |   |           |             |   |   |   |                            |        |
| <b>Fluks</b>  | $\int_C \vec{F} \cdot \vec{n} ds = \int_C F_1 dy - F_2 dx \quad \vec{n} = \vec{T} \times \vec{k}$   | <b>I planet</b>   |   |   |   |           |             |   |   |   |                            |        |
| <b>Fundamental-teoremet for kurve-integraler</b>                    | $\vec{F}$ vektorfelt med kontinuerlige komponenter over et åpent område D<br>$\Downarrow$<br>$\exists$ differensierbar funksjon $f: \vec{F} = \nabla f$<br>$\int_A^B \vec{F} \cdot d\vec{r} = f(B) - f(A)$  |   |   |   |   |           |             |   |   |   |                            |        |
| <b>Eksakt differensialform</b>                                      | $F_1 dx + F_2 dy + F_3 dz$ er en differensialform<br>En differensialform er eksakt hvis $M dx + N dy + P dz = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$<br>Differensialform $F_1 dx + F_2 dy + F_3 dz$ er eksakt<br>$\Updownarrow$<br>$\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z} \quad \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x} \quad \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$   |   |   |   |   |           |             |   |   |   |                            |        |
| <b>F konservativ (vei-uavhengig)</b>                                | $\int_C \vec{F} \cdot d\vec{r} = f(b) - f(a)$ $\oint_C \vec{F} \cdot d\vec{r} = 0$ $\vec{F} = \nabla f$ $\text{curl} \vec{F} = \nabla \times \vec{F} = \vec{0}$ <table style="width: 100%; border: none;"> <tr> <td style="text-align: center;"><math>\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}</math></td> <td style="text-align: center;"><math>\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}</math></td> <td style="text-align: center;"><math>\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}</math></td> <td style="text-align: center;"><math>\vec{F}</math></td> <td style="text-align: center;">Konservativ</td> </tr> <tr> <td style="text-align: center;"><math>\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}</math></td> <td style="text-align: center;"><math>\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}</math></td> <td style="text-align: center;"><math>\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}</math></td> <td style="text-align: center;"><math>F_1 dx + F_2 dy + F_3 dz</math></td> <td style="text-align: center;">Eksakt</td> </tr> </table> |   | $\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$ | $\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}$ | $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$ | $\vec{F}$ | Konservativ | $\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$ | $\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}$ | $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$ | $F_1 dx + F_2 dy + F_3 dz$ | Eksakt |
| $\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$ | $\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}$   | $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$ | $\vec{F}$   | Konservativ   |   |           |             |   |   |   |                            |        |
| $\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$ | $\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}$   | $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$ | $F_1 dx + F_2 dy + F_3 dz$  | Eksakt  |   |           |             |   |   |   |                            |        |

## Flate-integral

|                                      |   |   |
|--------------------------------------|---|---|
| <b>Flate-integral</b>                | $\iint_S g dS = \iint_R g(x, y, z) \frac{ \nabla f }{ \nabla f \cdot \vec{p} } dA$                | <b>Flate-areal</b> $\iint_S dS = \iint_R \frac{ \nabla f }{ \nabla f \cdot \vec{p} } dA$                |
| <b>Parameterisert flate-integral</b> | $\iint_S G(x, y, z) dS = \iint_R G(f(u, v), g(u, v), h(u, v))  \vec{r}_u \times \vec{r}_v  dudv$  | <b>Flate-areal</b> $\iint_S dS = \iint_R  \vec{r}_u \times \vec{r}_v  dudv$                             |
| <b>Fluks</b>                         | $\iint_S \vec{F} \cdot \vec{n} dS$  |   |
| <b>Enhetsnormalvektor</b>            | $\vec{n} = \frac{\nabla f}{ \nabla f }$ <b>f skalarfunksjon som har flaten S som en nivåflate</b> | $\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{ \vec{r}_u \times \vec{r}_v }$ <b>Parameterisert flate</b> |

## Green's teorem - Stoke's teorem

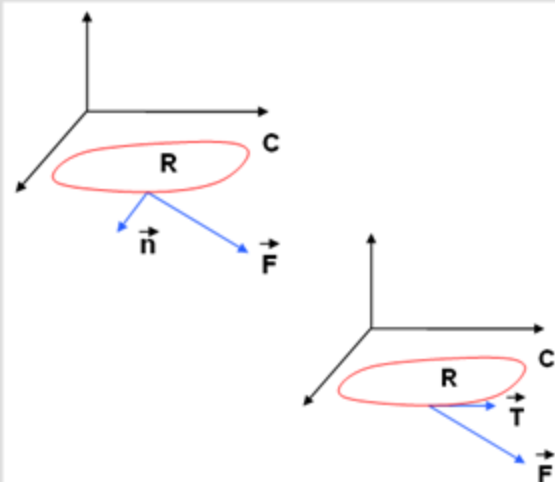
|  | 2D   | 3D   |                        |
|--|--|--|------------------------|
| <b>Green - Normalform</b><br><br>Divergens = Flukstetthet<br>$= \frac{\text{Fluks}}{\text{Areal}}$             | $\oint_C \vec{F} \cdot \vec{n} ds = \oint_C F_1 dy - F_2 dx$ $= \iint_R \left[ \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} \right] dx dy$ $= \iint_R \text{div} \vec{F} dA$ $= \iint_R \nabla \cdot \vec{F} dA$  | $\iiint_S \vec{F} \cdot \vec{n} dS = \iiint_S F_1 dy dz + F_2 dz dx + F_3 dx dy$ $= \iiint_D \left[ \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right] dx dy dz$ $= \iiint_D \text{div} \vec{F} dV$ $= \iiint_D \nabla \cdot \vec{F} dV$  | <b>Gauss Divergens</b> |
| <b>Green - Tangensialform</b><br><br>Curl = Sirkulasjonstetthet<br>$= \frac{\text{Sirkulasjon}}{\text{Areal}}$ | $\oint_C \vec{F} \cdot \vec{T} ds = \oint_C \vec{F} \cdot d\vec{r}$ $= \oint_C F_1 dx + F_2 dy$ $= \iint_R \left[ \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right] dx dy$ $= \iint_R \text{curl} \vec{F} \cdot \vec{k} dA$ $= \iint_R (\nabla \times \vec{F}) \cdot \vec{k} dA$ | $\oint_C \vec{F} \cdot \vec{T} ds = \oint_C \vec{F} \cdot d\vec{r}$ $= \oint_C F_1 dx + F_2 dy + F_3 dz$ $= \iint_S \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy dz + \left( \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) dz dx + \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy$ $= \iint_S \text{curl} \vec{F} \cdot \vec{n} dS$ $= \iint_S \nabla \times \vec{F} \cdot \vec{n} d\sigma$ | <b>Stoke</b>           |

2D**Green - Divergens**

$$\Phi = \oint_C \vec{F} \cdot \vec{n} ds = \iint_R \nabla \cdot \vec{F} dA$$

**Green - Curl**

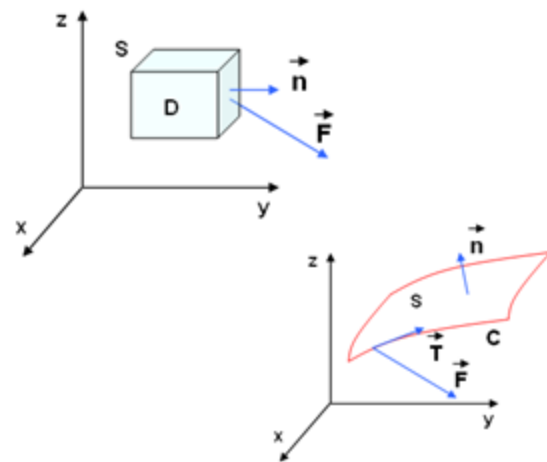
$$C = \oint_C \vec{F} \cdot \vec{T} ds = \iint_R (\nabla \times \vec{F}) \cdot \vec{k} dA$$

3D**Gauss - Divergens**

$$\Phi = \oint_S \vec{F} \cdot \vec{n} dS = \iiint_D \nabla \cdot \vec{F} dV$$

**Stokes - Curl**

$$C = \oint_C \vec{F} \cdot \vec{T} ds = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} dS$$



## Substitusjon i multiple integraler

|                  |   |
|------------------|---|
| <p><b>2D</b></p> | $\iint_D F(x, y) dx dy = \iint_D F(x(u, v), y(u, v))  J(u, v)  du dv$ $J(u, v) = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} \quad J^{-1}(x, y) = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} \quad J(u, v) J^{-1}(x, y) = 1$   |
| <p><b>3D</b></p> | $\iiint_D F(x, y, z) dx dy dz = \iiint_G F(x(u, v, w), y(u, v, w), z(u, v, w))  J(u, v, w)  du dv dw$ $J(u, v, w) = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix} \quad J^{-1}(x, y, z) = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix} \quad J(u, v, w) J^{-1}(x, y, z) = 1$ |

## Greens form av areal

|                                |   |
|--------------------------------|---|
| <p><b>Tangensiell form</b></p> | $A = \iint dA = \oint x dy \quad \oint F_1 dx + F_2 dy = \iint \left[ \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right] dA \quad F_2 = x \quad F_1 = 0$ $A = \iint dA = -\oint y dx \quad \oint F_1 dx + F_2 dy = \iint \left[ \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right] dA \quad F_2 = 0 \quad F_1 = -y$ |
| <p><b>Normalform</b></p>       | $A = \iint dA = \frac{1}{2} \oint x dy - y dx \quad \oint F_1 dy - F_2 dx = \iint \left[ \frac{\partial F_1}{\partial x} - \frac{\partial F_2}{\partial y} \right] dA \quad F_1 = \frac{1}{2} x \quad F_2 = \frac{1}{2} y$  |



Masse - Masse-senter - Trehetsmoment

|                      | Kurve  | Flate  | Volum  |
|----------------------|--|--|--|
| <b>Masse</b>         | $M = \int_C \delta l ds$   | $M = \iint_S \delta l dS$  | $M = \iiint_V \delta dV$   |
| <b>Masse-senter</b>  | $\bar{x} = \frac{1}{M} \int_C x \delta l ds$ $\bar{y} = \frac{1}{M} \int_C y \delta l ds$ $\bar{z} = \frac{1}{M} \int_C z \delta l ds$   | $\bar{x} = \frac{1}{M} \iint_S x \delta l dS$ $\bar{y} = \frac{1}{M} \iint_S y \delta l dS$  | $\bar{x} = \frac{1}{M} \iiint_V x \delta dV$ $\bar{y} = \frac{1}{M} \iiint_V y \delta dV$ $\bar{z} = \frac{1}{M} \iiint_V z \delta dV$   |
| <b>Trehetsmoment</b> | $I_x = \int_C (y^2 + z^2) \delta l ds$ $I_y = \int_C (x^2 + z^2) \delta l ds$ $I_z = \int_C (x^2 + y^2) \delta l ds$<br>$I_L = \int_C r^2 \delta l ds$<br>$R_L = \sqrt{\frac{I_L}{M}}$ | $I_x = \iint_S y^2 \delta dS$ $I_y = \iint_S x^2 \delta dS$<br>$I_L = \iint_S r^2 \delta dS$ $I_o = \iint_S (x^2 + y^2) \delta dS$<br>$R_L = \sqrt{\frac{I_L}{M}}$ | $I_x = \iiint_V (y^2 + z^2) \delta dV$ $I_y = \iiint_V (x^2 + z^2) \delta dV$ $I_z = \iiint_V (x^2 + y^2) \delta dV$<br>$I_L = \iiint_V r^2 \delta dV$<br>$R_L = \sqrt{\frac{I_L}{M}}$ |

## Fourier

|   |  |  |
|---|--|--|
| <p><b>Fourier-rekke (Periode 2L)</b></p>              | $f(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[ a_n \cos \frac{n\pi t}{L} + b_n \sin \frac{n\pi t}{L} \right]$ $a_n = \frac{1}{L} \int_{-L}^L f(t) \cos \frac{n\pi t}{L} dt \quad n = 0, 1, 2, 3, \dots$ $b_n = \frac{1}{L} \int_{-L}^L f(t) \sin \frac{n\pi t}{L} dt \quad n = 1, 2, 3, \dots$ | <p><b>Alternativt</b></p> $a_n = \frac{1}{L} \int_c^{c+2L} f(t) \cos \frac{n\pi t}{L} dt \quad n = 0, 1, 2, 3, \dots$ $b_n = \frac{1}{L} \int_c^{c+2L} f(t) \sin \frac{n\pi t}{L} dt \quad n = 1, 2, 3, \dots$ |
| <p><b>Even funksjon <math>f(-t) = f(t)</math></b></p> | $a_n = \frac{2}{L} \int_0^L f(t) \cos \frac{n\pi t}{L} dt \quad n = 0, 1, 2, 3, \dots$ $b_n = 0 \quad n = 1, 2, 3, \dots$  |  |
| <p><b>Odd funksjon <math>f(-t) = -f(t)</math></b></p> | $a_n = 0 \quad n = 0, 1, 2, 3, \dots$ $b_n = \frac{2}{L} \int_0^L f(t) \sin \frac{n\pi t}{L} dt \quad n = 1, 2, 3, \dots$  |  |

**Differensial-ligninger**

|                       |   |                           |
|-----------------------|---|---------------------------|
| <b>Svinge-ligning</b> | $m \frac{d^2 x}{dt^2} + c \frac{dx}{dt} + kx = F$                           | $mx_{tt} + cx_t + kx = F$ |
| <b>Bølge-ligning</b>  | $\frac{\partial^2 y}{\partial t^2} = v^2 \frac{\partial^2 y}{\partial x^2}$ | $y_{tt} = v^2 y_{xx}$     |
| <b>Varme-ligning</b>  | $\frac{\partial u}{\partial t} = \kappa \nabla^2 u$                         | $u_t = \kappa y_{xx}$     |

Svinge-ligning m / initialbetingelser

|  |   |   |
|--|---|---|
| <p><b>Kloss + fjær uten dempning</b></p> | $mx''+kx = F(t)$  | $0 \leq t \leq L$<br>$x(0) = 0$<br>$x(L) = 0$ |
|  | $x(t) = x_0(t) + x_p(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t) + x_p$<br><br>$F(t) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi t}{L}$<br>$b_n = \frac{2}{L} \int_0^L F(t) \sin \frac{n\pi t}{L} dt$<br><br>$x(t) = \sum_{n=1}^{\infty} B_n \sin \frac{n\pi t}{L}$<br>$= \sum_{n=1}^{\infty} \frac{1}{k - m \frac{n^2 \pi^2}{L^2}} b_n \sin \frac{n\pi t}{L}$ | $\omega_0 = \sqrt{\frac{k}{m}}$               |
| <p><b>Kloss + fjær med dempning</b></p>  | $mx''+cx'+kx = F(t)$  | $0 \leq t \leq L$<br>$x(0) = 0$<br>$x(L) = 0$ |
|  | $x_p(t) = \frac{F_0}{\sqrt{(k - m\omega^2)^2 + (c\omega)^2}} \sin(\omega t - \alpha)$<br>$\alpha = \tan^{-1} \frac{c\omega}{k - m\omega^2}$   | $F(t) = F_0 \sin(\omega t)$                   |
|  | $F(t) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi t}{L}$<br>$b_n = \frac{2}{L} \int_0^L F(t) \sin \frac{n\pi t}{L} dt$<br><br>$x(t) = \sum_{n=1}^{\infty} \frac{b_n \sin(\omega_n t - \alpha_n)}{(k - m\omega_n^2)^2 + (c\omega_n)^2}$  |   |

Varme- og bølge-ligning m / initialbetingelser

|  |  |  |
|--|--|--|
| <p><b>Varme-ligning</b><br/>m / initialbetingelser</p> <p><b>Fourier sinus-rekke</b></p> | $\frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2} \quad 0 < x < L$  | $u(0,t) = 0$ $u(L,t) = 0$ $u(x,0) = f(x)$  |
|  | $u(x,t) = \sum_{n=1}^{\infty} b_n e^{-\frac{n^2 \pi^2 k}{L^2} t} \sin \frac{n \pi x}{L}$ $b_n = \frac{2}{L} \int_0^L f(x) \sin \frac{n \pi x}{L} dx$ |  |
| <p><b>Bølge-ligning</b><br/>m / initialbetingelser</p> <p><b>Fourier sinus-rekke</b></p> | $\frac{\partial^2 y}{\partial t^2} = a^2 \frac{\partial^2 y}{\partial x^2} \quad 0 < x < L$  | $y(0,t) = 0$ $y(L,t) = 0$ $y(x,0) = f(x)$ $y_t(x,0) = g(x)$                      |
|  | $y(x,t) = \sum_{n=1}^{\infty} A_n \cos \frac{n \pi a t}{L} \sin \frac{n \pi x}{L}$ $A_n = \frac{2}{L} \int_0^L f(x) \sin \frac{n \pi x}{L} dx$       | <p><b>Problem A</b></p> $y(0,t) = 0$ $y(L,t) = 0$ $y(x,0) = f(x)$ $y_t(x,0) = 0$ |
|  | $y(x,t) = \sum_{n=1}^{\infty} B_n \sin \frac{n \pi a t}{L} \sin \frac{n \pi x}{L}$ $B_n = \frac{2}{n \pi a} \int_0^L g(x) \sin \frac{n \pi x}{L} dx$ | <p><b>Problem B</b></p> $y(0,t) = 0$ $y(L,t) = 0$ $y(x,0) = 0$ $y_t(x,0) = g(x)$ |
|  | $y(x,t) = y_A(x,t) + y_B(x,t)$   |  |